

Markov Chains

Note: Random variables are often treated as independent

- Often not the case
- Dependence exists between successive outcomes
- **Stochastic Process:** an indexed collection of random variables $\{X_t\}$

X_t = state of system (some measure or characteristic) at time t

$t \in T$, and T is often the set of non-negative integers

Ex. Daily sequence of high quotations of a particular stock

- Not series of IID random variables
- More like the following: $X_{t+1} = X_t + S_t$
 S_t 's may be IID, but X_t 's are not

Time in Stochastic Processes

- **Discrete Time**
 - Time can be regularly space (daily, weekly, etc.)
 - Can be imbedded - occurrences of some phenomenon in the system (each time the stock price reaches 100, or each time the inventory level reaches 0)
 - Sequence of realizations (i.e., outcomes) is called a **Time Series**
- **Continuous Time** - t can take on any value

Markov Property

- For general case of discrete time stochastic process with

$$X_t = i_t,$$

there must be a probability distribution on the sequence

$$P[X_0 = i_0, X_1 = i_1, X_2 = i_2, \dots, X_t = i_t, \dots]$$

- **Markov Property:** means that the state of the system at time $t+1$ only depends on the state of the system at t

$$\begin{aligned} P[X_{t+1} = i_{t+1} | X_t = i_t, X_{t-1} = i_{t-1}, \dots, X_1 = i_1, X_0 = i_0] \\ = P[X_{t+1} = i_{t+1} | X_t = i_t] \end{aligned}$$

Stationarity Assumption

- Probabilities are independent of t when the process is “stationary”

$$\text{So, } P[X_{t+1} = j | X_t = i] = p_{ij}$$

This means that if system is in state i , the probability that the system will transition to state j is p_{ij} no matter what the value of t is

Probabilities

- **Initial Probability distribution**
 - Defines the probability that the system starts in a particular state
 - Represented as: $P[X_0 = i] = q_i$ and
$$\bar{q} = (q_1, q_2, \dots, q_s)$$
 a vector
where $s = \text{number of states}$
- **Transition Probabilities displayed as $s \times s$ matrix**

$$P = \begin{pmatrix} p_{11} & p_{12} & \cdots & p_{1s} \\ p_{21} & p_{22} & \cdots & p_{2s} \\ \vdots & \vdots & \ddots & \vdots \\ p_{s1} & p_{s2} & \cdots & p_{ss} \end{pmatrix}$$

Simple Example

Weather:

- If it is raining today, it will rain tomorrow with probability $p_{rr} = 0.4$
- If it is raining today, it will not rain tomorrow with probability $p_{rn} = 0.6$
- If it is not raining today, it will rain tomorrow with probability $p_{nr} = 0.2$
- If it is not raining today, it will not rain tomorrow with probability $p_{nn} = 0.8$

Transition Matrix for Example

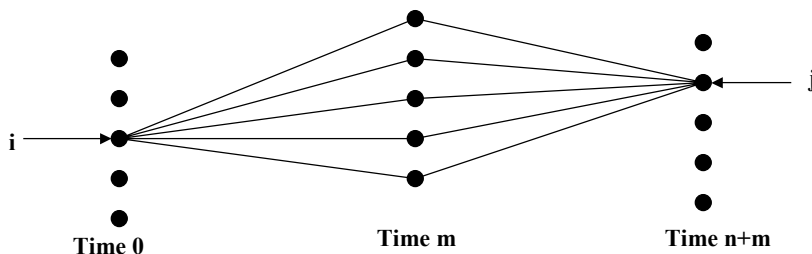
$$\mathbf{P} = \begin{pmatrix} .4 & .6 \\ .2 & .8 \end{pmatrix}$$

- Note that rows sum to 1
- Such a matrix is called a Stochastic Matrix
- If the rows of a matrix and the columns of a matrix all sum to 1, we have a Doubly Stochastic Matrix
- We'll use this matrix later

N Step Transition Probabilities

- Often the probability that the process is in a certain state n steps from now needs to be computed
 - Denoted $P_{ij}(n) = \text{Prob}\{\text{transition from } i \text{ to } j \text{ in } n \text{ steps}\}$

$$= P[X_{n+m} = j | X_m = i]$$



Chapman-Kolmogorov Equations

$$P_{ij}(n+m) = \sum_k P_{ik}(n)P_{kj}(m), \text{ for all } n, m \geq 0; \text{ and all } i, j$$

- This leads to a very important result:
 - $P_{ij}(n)$ is the ij^{th} element of the matrix P^n
 - P^n obtained by matrix multiplication of matrix P
 - P^n called the n step probability matrix
- Back to weather example:

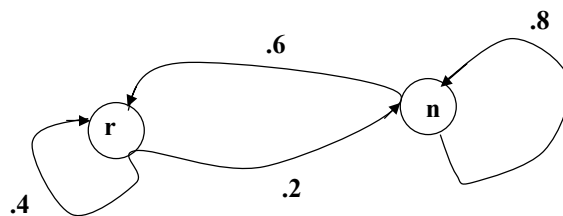
$$P^2 = \begin{pmatrix} .4 & .6 \\ .2 & .8 \end{pmatrix} \begin{pmatrix} .4 & .6 \\ .2 & .8 \end{pmatrix} = \begin{pmatrix} .16+.12 & .24+.28 \\ .08+.16 & .12+.64 \end{pmatrix} = \begin{pmatrix} .28 & .72 \\ .24 & .76 \end{pmatrix}$$

$\therefore P_{rr}(2) = 0.28$

Classification of States

- We now know probabilities associated with states
- We can classify the states of the system
 - Whether you can get from one state to another
 - Whether you can return to a state
- To help in classifying states, we use a state diagram

From the weather example:



Classification of States - Definitions

- Def: **Path** - a sequence of transitions from state i to state j exists and has positive probability, i.e., $P_{ij}(n) > 0$ for some n .
- Def: State j is **Reachable** from state i if there is a path from i to j
- Def: Two states, i and j , **Communicate** if j is reachable from i , and i is reachable from j .
- Def: A set of states S in a Markov Chain is a **closed set** if no state outside of S is reachable.
- Def: A state i is an **absorbing state** if $p_{ii} = 1$ (closed set with 1 member)

Classification of States - Definitions

(continued)

- **Example of Absorbing State - The Gambler's Ruin**
 - At each play we have the following:
 - Gambler wins \$1 with probability p , or
 - Gambler loses \$1 with probability $1-p$
 - Game ends when gambler goes broke, or gains a fortune of $\$N$
 - Then both $\$0$ and $\$N$ are absorbing states
- Def: A state i is a **transient state** if there exists a state j that is reachable from i , but i is not reachable from j .
- Def: A state is **recurrent** if it is not transient

Classification of States - Definitions

(continued)

- **Def:** State i is periodic with period $k > 1$ if k is the smallest number such that all paths leading from state i back to state i have a length which is a multiple of k (a recurrent state that is not periodic is called aperiodic)

- **Def:** If all states in a Markov Chain are recurrent, aperiodic, and communicate with one another (a “nice” chain), then the Markov Chain is said to Ergodic